

DeepX

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Abstract

This article presents a theory for an agent based on combining simple extensions of explorative agents.

1 Introduction

In “<http://www.ai-agents.com/PDF/ShallowX/shallowX.pdf>”, an agent is described called **ShallowX** which is an explorative agent. This article presents a theory for combining simple extensions of ShallowX agents into a larger agent. As with ShallowX, the theory can also be used as a design framework for a general agent. Both the theory and the general agent are called **DeepX**.

2 ShallowX recap

A diagram representing the general data flow around ShallowX is shown in figure 1.

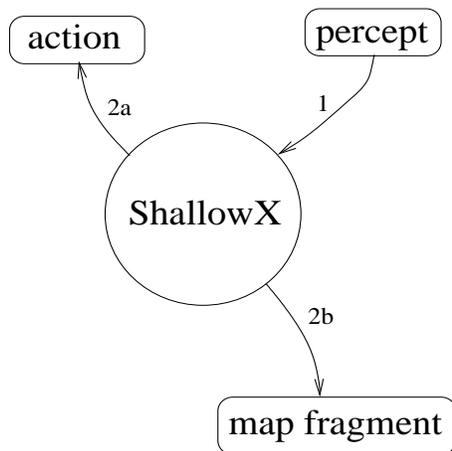


Figure 1: ShallowX data flow diagram.

The data named “**action**”, “**percept**” and “**map fragment**” are all finite symbol sequences and should be understood as follows:

- **percept** Sensory data from the environment.
- **action** Chosen action.
- **map fragment** Part of a map of the environment. The map fragment is on the form (C, I) , where C is a context, and I is information.

ShallowX continually acts and maps as a result of a never ending stream of percepts from the environment.

3 Initial combination

Using the diagram in figure 1 directly, an initial combination of the ShallowX agents is given in figure 2.

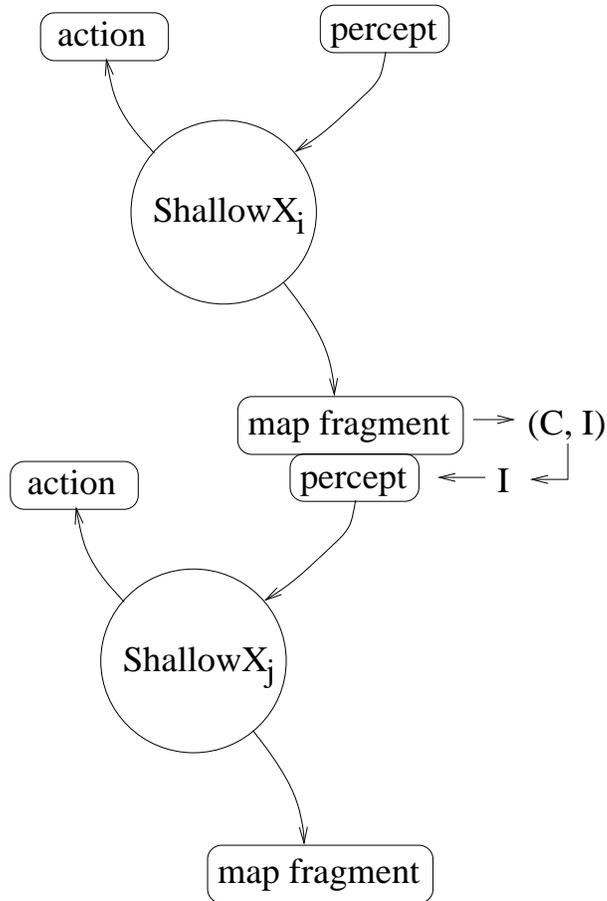


Figure 2: Initial ShallowX combination.

In figure 2, ShallowX_j has been added as a client of ShallowX_i receiving the latter's map fragment information, I . The client ShallowX_j is added to a location addressed by the map fragment context, C .

ShallowX_j is directly affected by ShallowX_i via percepts (the I part of ShallowX_i 's map fragment), but cannot directly affect ShallowX_i by its actions.

4 Extended combination

ShallowX_i might send a periodic signal to ShallowX_j and if the latter detects this, then it will emit an action in an attempt to explore something else. But the action emitted from ShallowX_j in figure 2 does not affect ShallowX_i directly. In order to achieve this, ShallowX is extended to **ShallowX+** as illustrated in figure 3.

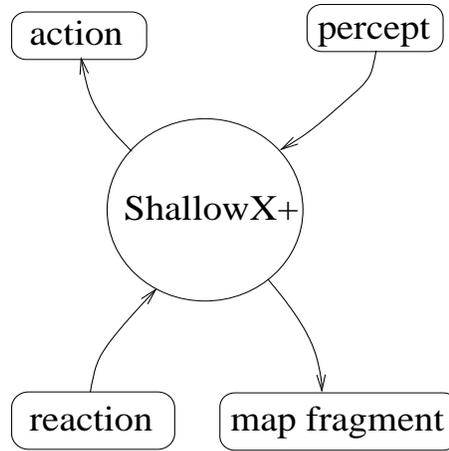


Figure 3: The extension of ShallowX to ShallowX+.

The added data named “**reaction**” is a finite symbol sequence and should be understood as being the client’s reaction to the delivered map fragment.

Now the diagram in figure 3 can be used to combine the ShallowX+ agents as illustrated in figure 4.

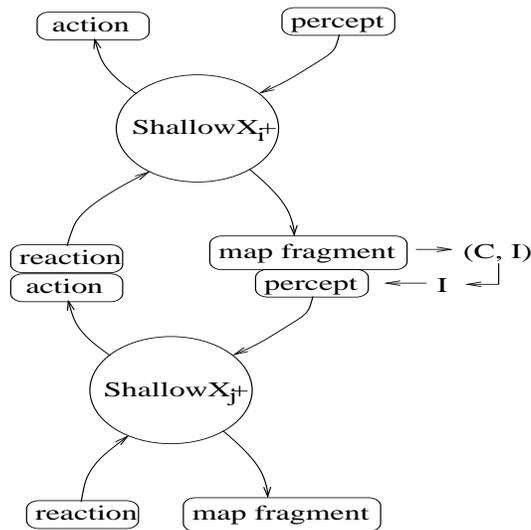


Figure 4: ShallowX+ combination.

4.1 Reaction location

If ShallowX_{j+} has detected a possible periodic signal coming from ShallowX_{i+} then ShallowX_{j+} can now affect ShallowX_{i+} by sending an action. To ShallowX_{i+} this

action is seen as a reaction coming from ShallowX_j+ . This reaction should affect ShallowX_i+ for as long as possible in order to stop the possible periodic signal sent to ShallowX_j+ . Hence the reaction is located at the beginning of ShallowX_i+ 's experience:

$$\text{reaction.experience}$$

The concatenation then becomes the new experience as in the following example:

$$\begin{aligned} \text{reaction} &= 10 \\ \text{experience} &= 1101010001 \\ \text{reaction.experience} &= 10.1101010001 \\ \text{new experience} &= 101101010001 \end{aligned}$$

4.2 Asynchronous calls

After ShallowX_i+ has called ShallowX_j+ with a percept, it does not wait for ShallowX_j+ to return an action. The reason is that ShallowX_j+ might not return an action since there might not be an overlap in ShallowX_j+ 's concatenated potential. Still, a “callback” link from ShallowX_j+ to ShallowX_i+ is created so that ShallowX_j+ can return its action when it is ready—possibly after more than one percept. After the action is returned, the callback link is removed.

The calls are then asynchronous avoiding $\text{ShallowX}+$ agents blocking when they have sent map fragments to their clients.

4.3 Message loss

As figure 3 illustrates, a $\text{ShallowX}+$ agent can receive a percept from its environment or it can receive a reaction from a client. After receiving input, $\text{ShallowX}+$ processes it and is not available for other inputs until the processing is completed returning a map fragment or an action. If other percepts or reactions are sent to $\text{ShallowX}+$ while it is processing, then these inputs are lost.

The main argument for accepting message loss is simplicity avoiding the need for extension by a queueing system.

It can also be argued, that if the environment is almost static then the input from the environment will be close to periodic. It is then possible that $\text{ShallowX}+$ can still detect such a period even though some messages are lost and hence choose an action in order to explore new parts of the environment. As for the map fragment, it may not be considered as correct, but it is still a map of what $\text{ShallowX}+$ perceives of the environment.

Ultimately, if a $\text{ShallowX}+$ agent is directly exposed to the physical environment then there will always be a loss of input and this observation can be used to argue in favor of allowing message loss across all $\text{ShallowX}+$ agents in DeepX .

4.4 Multiple callers

Consider figure 4 and observe that ShallowX_j+ can actually receive many percepts from ShallowX_i+ before it returns an action. The reason is that the first percepts received by ShallowX_j+ may not make it detect an overlap—that may require many percepts. But more than that, ShallowX_j+ can also receive percepts from other callers, ShallowX_k+ , as illustrated in Figure 5.

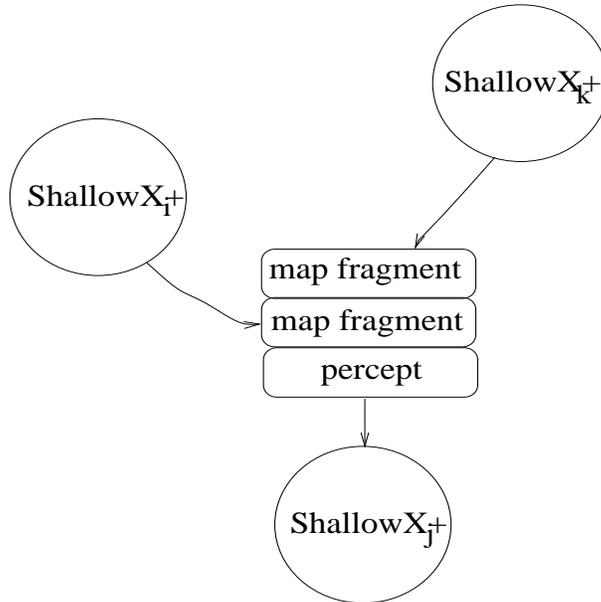


Figure 5: ShallowX+ with multiple callers.

The percept from ShallowX_{i+} is received before the percept from ShallowX_{k+}. Callback links to both ShallowX_{i+} and ShallowX_{k+} are created in order to return ShallowX_{j+}'s action to both callers when the action is ready. After the action is returned, the links are removed. This scheme generalizes to arbitrarily many callers of ShallowX_{j+}.

The reason for using this scheme of multiple callers is to allow for different parts of DeepX to combine their map fragments into a single part that gets a more nuanced view of the environment. The single part can then also detect possible overlaps between the different parts that affect it and hence communicate this mutual overlap back.

5 Summary

The **DeepX** agent has been defined based on combinations of extensions of **ShallowX** agents. DeepX can be an arbitrarily deep network of explorative ShallowX+ agents.

6 Ideas for future work

The question is how the DeepX network of explorative agents will react to phenomena of varying complexity occurring in the physical world. An implementation of DeepX is desired in order to help with an answer.